

Package ‘SdeaR’

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Type Package

Title Stochastic Data Envelopment Analysis

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Description

Set of functions for Stochastic Data Envelopment Analysis. Chance constrained versions of radial, directional and additive DEA models are implemented, as long as super-efficiency models. See: Cooper, W.W.; Deng, H.; Huang, Z.; Li, S.X. (2002). <[doi:10.1057/palgrave.jors.2601433](https://doi.org/10.1057/palgrave.jors.2601433)>, Bolós, V.J.; Benítez, R.; Serrano, V. (2024) <[doi:10.1016/j.orp.2024.100307](https://doi.org/10.1016/j.orp.2024.100307)>.

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Automobile	<i>Data: Cooper et al. (2001).</i>
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Description

Data of automobile industries collected from the Statistical Year Book of China of the Chinese Bureau of Statistics. Each year is treated as a DMU.

Usage

```
data("Automobile")
```

Format

Data frame with 17 rows and 4 columns. Definition of inputs (X) and output (Y):

X1 = Labor Expressed in units of 1000 persons.

X2 = Capital Stated in units of 1 million Ren Min Bi (Chinese monetary unit) adjusted to 1991 prices.

Y = Output Stated in units of 1 million Ren Min Bi (Chinese monetary unit) adjusted to 1991 prices.

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Source

Cooper, W.W.; Denga, H.; Gua, B.; Lib, S.; Thrall, R.M. (2001). "Using DEA to improve the management of congestion in Chinese industries (1981-1997)", *Socio-Economic Planning Sciences*, 35(4), 227-242.

See Also

[make_deadata_stoch](#), [modelstoch_radial](#)


```

                                var_output = var_output)
Collstoch <- modelstoch_radial(data_stoch)
efficiencies(Collstoch)

```

make_deadata_stoch *make_deadata_stoch*

Description

This function creates, from a deadata object, a deadata_stoch object by adding the corresponding covariance matrices. These objects are prepared to be passed to a modelstoch_* function.

We consider $\mathcal{D} = \{\text{DMU}_1, \dots, \text{DMU}_n\}$ a set of n DMUs with m stochastic inputs and s stochastic outputs. Matrices $\tilde{X} = (\tilde{x}_{ij})$ and $\tilde{Y} = (\tilde{y}_{rj})$ are the input and output data matrices, respectively, where \tilde{x}_{ij} and \tilde{y}_{rj} represent the i -th input and r -th output of the j -th DMU. Moreover, we denote by $X = (x_{ij})$ and $Y = (y_{rj})$ their expected values. We suppose that \tilde{x}_{ij} and \tilde{y}_{rj} follow a multivariate probability distribution with means $E(\tilde{x}_{ij}) = x_{ij}$, $E(\tilde{y}_{rj}) = y_{rj}$ and covariance matrix

$$\Delta = \begin{pmatrix} \Delta_{11}^{II} & \dots & \Delta_{1m}^{II} & \Delta_{11}^{IO} & \dots & \Delta_{1s}^{IO} \\ \vdots & & \vdots & \vdots & & \vdots \\ \Delta_{m1}^{II} & \dots & \Delta_{mm}^{II} & \Delta_{m1}^{IO} & \dots & \Delta_{ms}^{IO} \\ \Delta_{11}^{OI} & \dots & \Delta_{1m}^{OI} & \Delta_{11}^{OO} & \dots & \Delta_{1s}^{OO} \\ \vdots & & \vdots & \vdots & & \vdots \\ \Delta_{s1}^{OI} & \dots & \Delta_{sm}^{OI} & \Delta_{s1}^{OO} & \dots & \Delta_{ss}^{OO} \end{pmatrix}_{n(m+s) \times n(m+s)}$$

where Δ_{ik}^{II} , Δ_{rp}^{OO} , Δ_{ir}^{IO} and Δ_{ri}^{OI} are $n \times n$ matrices, for $1 \leq i, k \leq m$ and $1 \leq r, p \leq s$, such that

$$\begin{aligned} (\Delta_{ik}^{II})_{jq} &= \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{kq}), \\ (\Delta_{rp}^{OO})_{jq} &= \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{pq}), \\ (\Delta_{ir}^{IO})_{jq} &= (\Delta_{ri}^{OI})_{qj} = \text{Cov}(\tilde{x}_{ij}, \tilde{y}_{rq}), \end{aligned}$$

with $1 \leq j, q \leq n$.

- If we have the covariances matrix in the general form above, it can be introduced directly by parameter `cov_matrix`. Since this matrix is supposed to be symmetric, only values above the diagonal are read, ignoring values below the diagonal.

- Alternatively, we can introduce the covariances matrix using parameters `cov_II`, `cov_00` and `cov_I0`, that are 4-dimensional arrays of size $m \times m \times n \times n$, $s \times s \times n \times n$ and $m \times s \times n \times n$, respectively, such that

$$\begin{aligned} \text{cov_II}[i, k, ,] &= \Delta_{ik}^{II}, \\ \text{cov_00}[r, p, ,] &= \Delta_{rp}^{OO}, \\ \text{cov_I0}[i, r, ,] &= \Delta_{ir}^{IO}, \end{aligned}$$

for $1 \leq i, k \leq m$ and $1 \leq r, p \leq s$. Since matrices Δ_{ii}^{II} and Δ_{rr}^{OO} are supposed to be symmetric, only values above the diagonal are read, ignoring values below the diagonal. Moreover, since Δ_{ki}^{II} is the transpose of Δ_{ik}^{II} , and Δ_{pr}^{OO} is the transpose of Δ_{rp}^{OO} , only matrices Δ_{ik}^{II} and Δ_{rp}^{OO} with $i \leq k$ and $r \leq p$ are necessary, ignoring those with $i > k$ and $r > p$.

- If covariances between different inputs/outputs are zero, we can make use of parameters `cov_input` and `cov_output`, that are arrays of size $m \times n \times n$ and $s \times n \times n$, respectively, such that

$$\text{cov_input}[i, ,] = \Delta_{ii}^{II},$$

$$\text{cov_output}[r, ,] = \Delta_{rr}^{OO},$$

for $1 \leq i \leq m$ and $1 \leq r \leq s$. By symmetry of Δ_{ii}^{II} and Δ_{rr}^{OO} , only values above the diagonal are read, ignoring values below the diagonal.

- Finally, if all the variables are independent then the covariances matrix is diagonal. Hence, we might use parameters `var_input` and `var_output`, that are matrices of size $m \times n$ and $s \times n$, respectively, such that

$$\text{var_input}[i, j] = \text{Var}(\tilde{x}_{ij}),$$

$$\text{var_output}[r, j] = \text{Var}(\tilde{y}_{rj}),$$

for $1 \leq i \leq m, 1 \leq r \leq s$ and $1 \leq j \leq n$.

Usage

```
make_deadata_stoch(datadea = NULL,
  var_input = NULL,
  var_output = NULL,
  cov_input = NULL,
  cov_output = NULL,
  cov_II = NULL,
  cov_OO = NULL,
  cov_IO = NULL,
  cov_matrix = NULL)
```

Arguments

<code>datadea</code>	The deadata object.
<code>var_input</code>	A matrix of size $m \times n$, where m is the number of inputs and n is the number of DMUs. It contains the variances of each input of each DMU, such that <code>var_input[i, j]</code> is the variance of the input i of DMU j . Use this parameter if all covariances are 0.
<code>var_output</code>	A matrix of size $s \times n$, where s is the number of outputs and n is the number of DMUs. It contains the variances of each output of each DMU, such that <code>var_output[r, j]</code> is the variance of the output r of DMU j . Use this parameter if all covariances are 0.
<code>cov_input</code>	An array of size $m \times n \times n$ containing the covariances of each input between DMUs, such that <code>cov_input[i, j, k]</code> is the covariance between the input i of DMU j and the input i of DMU k . The corresponding variances are in the diagonal of each $n \times n$ submatrix. Since these submatrices are supposed to be

	symmetric, only values above the diagonal are read in order to reconstruct the symmetric submatrices, ignoring values below the diagonal. Use this parameter if covariances between different inputs are 0.
cov_output	An array of size $s \times n \times n$ containing the covariances of each output between DMUs, such that $\text{cov_output}[r, j, k]$ is the covariance between the output r of DMU j and the output r of DMU k . The corresponding variances are in the diagonal of each $n \times n$ submatrix. Since these submatrices are supposed to be symmetric, only values above the diagonal are read in order to reconstruct the symmetric submatrices, ignoring values below the diagonal. Use this parameter if covariances between different outputs are 0.
cov_II	An array of size $m \times m \times n \times n$ containing the covariances between inputs and between DMUs, such that $\text{cov_II}[i1, i2, j, k]$ is the covariance between the input $i1$ of DMU j and the input $i2$ of DMU k . For the input i , the corresponding variances are in the diagonal of the $n \times n$ submatrices of the form $\text{cov_II}[i, i, ,]$. Since these submatrices are supposed to be symmetric, only values above the diagonal are read in order to reconstruct the symmetric submatrices, ignoring values below the diagonal. Moreover, since $\text{cov_II}[i2, i1, ,]$ is the transpose of $\text{cov_II}[i1, i2, ,]$, only submatrices $\text{cov_II}[i1, i2, ,]$ with $i1 \leq i2$ are necessary, ignoring those with $i1 > i2$. Use this parameter if covariances between inputs are nonzero.
cov_00	An array of size $s \times s \times n \times n$ containing the covariances between outputs and between DMUs, such that $\text{cov_00}[r1, r2, j, k]$ is the covariance between the output $r1$ of DMU j and the output $r2$ of DMU k . For the output r , the corresponding variances are in the diagonal of the $n \times n$ submatrices of the form $\text{cov_00}[r, r, ,]$. Since these submatrices are supposed to be symmetric, only values above the diagonal are read in order to reconstruct the symmetric submatrices, ignoring values below the diagonal. Moreover, since $\text{cov_00}[r2, r1, ,]$ is the transpose of $\text{cov_00}[r1, r2, ,]$, only submatrices $\text{cov_00}[r1, r2, ,]$ with $r1 \leq r2$ are necessary, ignoring those with $r1 > r2$. Use this parameter if covariances between outputs are nonzero.
cov_IO	An array of size $m \times s \times n \times n$ containing the covariances between inputs and outputs, and between DMUs, such that $\text{cov_IO}[i, r, j, k]$ is the covariance between the input i of DMU j and the output r of DMU k . Use this parameter if covariances between inputs and outputs are nonzero.
cov_matrix	A matrix of size $n(m+s) \times n(m+s)$ following the notation of Cooper et al. (1998). Since this matrix is supposed to be symmetric, only values above the diagonal are read, ignoring values below the diagonal.

Value

An object of class `deadata_stoch`.

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References

Cooper, W.W.; Huang, Z.; Lelas, V.; Li, S.X.; Olesen, O.B. (1998). "Chance Constrained Programming Formulations for Stochastic Characterizations of Efficiency and Dominance in DEA", *Journal of Productivity Analysis*, 9, 53-79.

El-Demerdash, B.E.; El-Khodary, I.A.; Tharwat, A.A. (2013). "Developing a Stochastic Input Oriented Data Envelopment Analysis (SIODEA) Model", *International Journal of Advanced Computer Science and Applications*, Vol.4, No. 4, 40-44.

Examples

```
# Example 1
library(deaR)
data("Coll_Blasco_2006")
ni <- 2 # number of inputs
no <- 2 # number of outputs
data_example <- make_deadata(datadea = Coll_Blasco_2006,
                             ni = ni,
                             no = no)

nd <- length(data_example$dmunames) # number of DMUs
# All variances are 1.
var_input <- matrix(1, nrow = ni, ncol = nd)
var_output <- matrix(1, nrow = no, ncol = nd)
data_stoch <- make_deadata_stoch(datadea = data_example,
                                var_input = var_input,
                                var_output = var_output)

# All covariances are 1.
cov_input <- array(1, dim = c(ni, nd, nd))
cov_output <- array(1, dim = c(no, nd, nd))
data_stoch2 <- make_deadata_stoch(datadea = data_example,
                                 cov_input = cov_input,
                                 cov_output = cov_output)

# Example 2. Deterministic data with one stochastic input,
# from El-Demerdash et al. (2013).
library(deaR)
dmunames <- c("A", "B", "C")
nd <- length(dmunames) # Number of DMUs
inputnames <- c("Professors", "Budget")
ni <- length(inputnames) # Number of Inputs
outputnames <- c("Diplomas", "Bachelors", "Masters")
no <- length(outputnames) # Number of Outputs
X <- matrix(c(5, 14, 8, 15, 7, 12),
            nrow = ni, ncol = nd, dimnames = list(inputnames, dmunames))
Y <- matrix(c(9, 4, 16, 5, 7, 10, 4, 9, 13),
            nrow = no, ncol = nd, dimnames = list(outputnames, dmunames))
datadea <- make_deadata(inputs = X,
```

```

                                outputs = Y)
covX <- array(0, dim = c(2, 3, 3))
# The 2nd input is stochastic.
# Since the corresponding 3x3 covariances matrix is symmetric, only values
# above the diagonal are necessary.
covX[2, 1, ] <- c(1.4, 0.9, 0.6)
covX[2, 2, 2:3] <- c(1.5, 0.7)
covX[2, 3, 3] <- 1.2
# Alternatively (note that values below the diagonal are ignored).
covX[2, , ] <- matrix(c(1.4, 0.9, 0.6, 0, 1.5, 0.7, 0, 0, 1.2),
                      byrow = TRUE)
datadea_stoch <- make_deadata_stoch(datadea,
                                   cov_input = covX)

# Example 3. 5 random observations of 3 DMUs with 2 inputs and 2 outputs.
library(deaR)
# Generate random observations.
input1 <- data.frame(I1D1 = rnorm(5, mean = sample(5:10, 1)),
                    I1D2 = rnorm(5, mean = sample(5:10, 1)),
                    I1D3 = rnorm(5, mean = sample(5:10, 1)))
input2 <- data.frame(I2D1 = rnorm(5, mean = sample(5:10, 1)),
                    I2D2 = rnorm(5, mean = sample(5:10, 1)),
                    I2D3 = rnorm(5, mean = sample(5:10, 1)))
output1 <- data.frame(O1D1 = rnorm(5, mean = sample(5:10, 1)),
                    O1D2 = rnorm(5, mean = sample(5:10, 1)),
                    O1D3 = rnorm(5, mean = sample(5:10, 1)))
output2 <- data.frame(O2D1 = rnorm(5, mean = sample(5:10, 1)),
                    O2D2 = rnorm(5, mean = sample(5:10, 1)),
                    O2D3 = rnorm(5, mean = sample(5:10, 1)))
# Generate deadata with means of observations.
inputs <- matrix(mapply(mean, cbind(input1, input2)),
                nrow = 2,
                ncol = 3,
                byrow = TRUE,
                dimnames = list(c("I1", "I2"), c("D1", "D2", "D3")))
outputs <- matrix(mapply(mean, cbind(output1, output2)),
                 nrow = 2,
                 ncol = 3,
                 byrow = TRUE,
                 dimnames = list(c("O1", "O2"), c("D1", "D2", "D3")))
datadea <- make_deadata(inputs = inputs,
                       outputs = outputs)
# Generate covariances matrix cov_matrix.
cov_matrix <- cov(cbind(input1, input2, output1, output2))
# Generate deadata_stoch
datadea_stoch <- make_deadata_stoch(datadea,
                                   cov_matrix = cov_matrix)

```

Description

It solves the chance constrained additive E-model based on the deterministic additive model from Charnes et al. (1985), under constant and non-constant returns to scale.

Besides, the user can set weights for the input and/or output slacks. So, it is also possible to solve chance constrained versions of weighted additive models like Measure of Inefficiency Proportions (MIP) or Range Adjusted Measure (RAM), see Cooper et al. (1999).

We consider $\mathcal{D} = \{\text{DMU}_1, \dots, \text{DMU}_n\}$ a set of n DMUs with m stochastic inputs and s stochastic outputs. Matrices $\tilde{X} = (\tilde{x}_{ij})$ and $\tilde{Y} = (\tilde{y}_{rj})$ are the input and output data matrices, respectively, where \tilde{x}_{ij} and \tilde{y}_{rj} represent the i -th input and r -th output of the j -th DMU. Moreover, we denote by $X = (x_{ij})$ and $Y = (y_{rj})$ their expected values. In general, we denote vectors by bold-face letters and they are considered as column vectors unless otherwise stated. The 0-vector is denoted by $\mathbf{0}$ and the context determines its dimension.

Given $0 < \alpha < 1$, the program for DMU_o with constant returns to scale is given by

$$\begin{aligned} & \max_{\lambda, \mathbf{s}^-, \mathbf{s}^+} \quad \mathbf{w}^- \mathbf{s}^- + \mathbf{w}^+ \mathbf{s}^+ \\ \text{s.t.} \quad & P \left\{ \left(\tilde{\mathbf{x}}_o - \tilde{X} \boldsymbol{\lambda} - \mathbf{s}^- \right)_i \geq 0 \right\} \geq 1 - \alpha, \quad i = 1, \dots, m, \\ & P \left\{ \left(\tilde{Y} \boldsymbol{\lambda} - \tilde{\mathbf{y}}_o - \mathbf{s}^+ \right)_r \geq 0 \right\} \geq 1 - \alpha, \quad r = 1, \dots, s, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \mathbf{s}^- \geq \mathbf{0}, \mathbf{s}^+ \geq \mathbf{0}, \end{aligned}$$

where $\boldsymbol{\lambda} = (\lambda_1, \dots, \lambda_n)^\top$, $\tilde{\mathbf{x}}_o = (\tilde{x}_{1o}, \dots, \tilde{x}_{mo})^\top$ and $\tilde{\mathbf{y}}_o = (\tilde{y}_{1o}, \dots, \tilde{y}_{so})^\top$ are column vectors. Moreover, $\mathbf{s}^-, \mathbf{s}^+$ are column vectors with the slacks, and $\mathbf{w}^-, \mathbf{w}^+$ are positive row vectors with the weights for the slacks. Different returns to scale can be easily considered by adding the corresponding constraints: $\mathbf{e} \boldsymbol{\lambda} = 1$ (VRS), $0 \leq \mathbf{e} \boldsymbol{\lambda} \leq 1$ (NIRS), $\mathbf{e} \boldsymbol{\lambda} \geq 1$ (NDRS) or $L \leq \mathbf{e} \boldsymbol{\lambda} \leq U$ (GRS), with $0 \leq L \leq 1$ and $U \geq 1$, where $\mathbf{e} = (1, \dots, 1)$ is a row vector.

The deterministic equivalent for a multivariate normal distribution of inputs/outputs is given by

$$\begin{aligned} & \max_{\lambda, \mathbf{s}^-, \mathbf{s}^+} \quad \mathbf{w}^- \mathbf{s}^- + \mathbf{w}^+ \mathbf{s}^+ \\ \text{s.t.} \quad & \mathbf{x}_o - X \boldsymbol{\lambda} - \mathbf{s}^- + \Phi^{-1}(\alpha) \boldsymbol{\sigma}^-(\boldsymbol{\lambda}) \geq \mathbf{0}, \\ & Y \boldsymbol{\lambda} - \mathbf{y}_o - \mathbf{s}^+ + \Phi^{-1}(\alpha) \boldsymbol{\sigma}^+(\boldsymbol{\lambda}) \geq \mathbf{0}, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \mathbf{s}^- \geq \mathbf{0}, \mathbf{s}^+ \geq \mathbf{0}, \end{aligned}$$

where Φ is the standard normal distribution, and

$$\begin{aligned} (\sigma_i^-(\boldsymbol{\lambda}))^2 &= \sum_{j,q=1}^n \lambda_j \lambda_q \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{iq}) - 2 \sum_{j=1}^n \lambda_j \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{io}) \\ &\quad + \text{Var}(\tilde{x}_{io}), \quad i = 1, \dots, m, \\ (\sigma_r^+(\boldsymbol{\lambda}))^2 &= \sum_{j,q=1}^n \lambda_j \lambda_q \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{rq}) - 2 \sum_{j=1}^n \lambda_j \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{ro}) \\ &\quad + \text{Var}(\tilde{y}_{ro}), \quad r = 1, \dots, s. \end{aligned}$$

Usage

```

modelstoch_additive(datadea,
  alpha = 0.05,
  dmu_eval = NULL,
  dmu_ref = NULL,
  orientation = NULL,
  weight_slack_i = 1,
  weight_slack_o = 1,
  rts = c("crs", "vrs", "nirs", "ndrs", "grs"),
  L = 1,
  U = 1,
  solver = c("alabama", "cccp", "cccp2", "slsqp"),
  give_X = TRUE,
  returnqp = FALSE,
  ...)

```

Arguments

<code>datadea</code>	The data of class <code>deadata_stoch</code> , including n DMUs, and the expected values of m inputs and s outputs.
<code>alpha</code>	A value for parameter α .
<code>dmu_eval</code>	A numeric vector containing which DMUs have to be evaluated. If <code>NULL</code> (default), all DMUs are considered.
<code>dmu_ref</code>	A numeric vector containing which DMUs are the evaluation reference set. If <code>NULL</code> (default), all DMUs are considered.
<code>orientation</code>	This parameter is either <code>NULL</code> (default) or a string, equal to "io" (input-oriented) or "oo" (output-oriented). It is used to modify the weight slacks. If input-oriented, <code>weight_slack_o</code> are taken 0. If output-oriented, <code>weight_slack_i</code> are taken 0.
<code>weight_slack_i</code>	A value, vector of length m , or matrix $m \times n_e$ (where n_e is the length of <code>dmu_eval</code>) with the weights of the input slacks. If 0, output-oriented.
<code>weight_slack_o</code>	A value, vector of length s , or matrix $s \times n_e$ (where n_e is the length of <code>dmu_eval</code>) with the weights of the output slacks. If 0, input-oriented.
<code>rts</code>	A string, determining the type of returns to scale, equal to "crs" (constant), "vrs" (variable), "nirs" (non-increasing), "ndrs" (non-decreasing) or "grs" (generalized).
<code>L</code>	Lower bound for the generalized returns to scale (grs).
<code>U</code>	Upper bound for the generalized returns to scale (grs).
<code>solver</code>	Character string with the name of the solver used by function <code>solvecop</code> from package <code>optiSolve</code> .
<code>give_X</code>	Logical. If it is <code>TRUE</code> , it uses an initial vector (given by the evaluated DMU) for the solver, except for "cccp". If it is <code>FALSE</code> , the initial vector is given internally by the solver and it is usually randomly generated.
<code>returnqp</code>	Logical. If it is <code>TRUE</code> , it returns the quadratic problems (objective function and constraints).
<code>...</code>	Other parameters, like the initial vector X , to be passed to the solver.

Value

A list with the results for the evaluated DMUs and other parameters for reproducibility.

Note

A DMU is α -stochastically efficient if and only if the optimal objective value of the problem, (objval), is zero (or less than zero).

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References

Charnes, A.; Cooper, W.W.; Golany, B.; Seiford, L.; Stuz, J. (1985) "Foundations of Data Envelopment Analysis for Pareto-Koopmans Efficient Empirical Production Functions", *Journal of Econometrics*, 30(1-2), 91-107. doi:10.1016/03044076(85)901332

Cooper, W.W.; Park, K.S.; Pastor, J.T. (1999). "RAM: A Range Adjusted Measure of Inefficiencies for Use with Additive Models, and Relations to Other Models and Measures in DEA". *Journal of Productivity Analysis*, 11, p. 5-42. doi:10.1023/A:1007701304281

modelstoch_additive_p *Chance Constrained Additive P-model.*

Description

It solves the "max" version of the "almost 100 chance constrained problem from Cooper et al. (1998), under constant and non-constant returns to scale.

Besides, the user can set weights for the input and/or output slacks. So, it is also possible to solve chance constrained versions of weighted additive models like Measure of Inefficiency Proportions (MIP) or Range Adjusted Measure (RAM), see Cooper et al. (1999).

We consider $\mathcal{D} = \{DMU_1, \dots, DMU_n\}$ a set of n DMUs with m stochastic inputs and s stochastic outputs. Matrices $\tilde{X} = (\tilde{x}_{ij})$ and $\tilde{Y} = (\tilde{y}_{rj})$ are the input and output data matrices, respectively, where \tilde{x}_{ij} and \tilde{y}_{rj} represent the i -th input and r -th output of the j -th DMU. Moreover, we denote by $X = (x_{ij})$ and $Y = (y_{rj})$ their expected values. In general, we denote vectors by bold-face letters and they are considered as column vectors unless otherwise stated. The 0-vector is denoted by $\mathbf{0}$ and the context determines its dimension.

Given $0 < \alpha < 1$ and ε a positive non-Archimedean infinitesimal, the program for DMU_o with constant returns to scale is given by

$$\max_{\lambda} P \left\{ \mathbf{w}^- \cdot (\tilde{\mathbf{x}}_o - \tilde{X}\lambda) + \mathbf{w}^+ \cdot (\tilde{Y}\lambda - \tilde{\mathbf{y}}_o) > 0 \right\}$$

$$\begin{aligned} \text{s.t. } & P \left\{ \left(\tilde{\mathbf{x}}_o - \tilde{X}\boldsymbol{\lambda} \right)_i > 0 \right\} \geq 1 - \varepsilon, \quad i = 1, \dots, m, \\ & P \left\{ \left(\tilde{Y}\boldsymbol{\lambda} - \tilde{\mathbf{y}}_o \right)_r > 0 \right\} \geq 1 - \varepsilon, \quad r = 1, \dots, s, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \end{aligned}$$

where $\boldsymbol{\lambda} = (\lambda_1, \dots, \lambda_n)^\top$, $\tilde{\mathbf{x}}_o = (\tilde{x}_{1o}, \dots, \tilde{x}_{mo})^\top$ and $\tilde{\mathbf{y}}_o = (\tilde{y}_{1o}, \dots, \tilde{y}_{so})^\top$ are column vectors. Moreover, \mathbf{w}^- , \mathbf{w}^+ are positive row vectors with the weights for the slacks. Different returns to scale can be easily considered by adding the corresponding constraints: $\mathbf{e}\boldsymbol{\lambda} = 1$ (VRS), $0 \leq \mathbf{e}\boldsymbol{\lambda} \leq 1$ (NIRS), $\mathbf{e}\boldsymbol{\lambda} \geq 1$ (NDRS) or $L \leq \mathbf{e}\boldsymbol{\lambda} \leq U$ (GRS), with $0 \leq L \leq 1$ and $U \geq 1$, where $\mathbf{e} = (1, \dots, 1)$ is a row vector.

The deterministic equivalent for a multivariate normal distribution of inputs/outputs is given by

$$\begin{aligned} \max_{\boldsymbol{\lambda}} \quad & \mathbf{w}^- \cdot (\mathbf{x}_o - X\boldsymbol{\lambda}) + \mathbf{w}^+ \cdot (Y\boldsymbol{\lambda} - \mathbf{y}_o) - \Phi^{-1}(\alpha)\sigma(\boldsymbol{\lambda}) \\ \text{s.t.} \quad & \mathbf{x}_o - X\boldsymbol{\lambda} + \Phi^{-1}(\varepsilon)\boldsymbol{\sigma}^-(\boldsymbol{\lambda}) \geq \mathbf{0}, \\ & Y\boldsymbol{\lambda} - \mathbf{y}_o + \Phi^{-1}(\varepsilon)\boldsymbol{\sigma}^+(\boldsymbol{\lambda}) \geq \mathbf{0}, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \end{aligned}$$

where Φ is the standard normal distribution, and

$$\begin{aligned} (\sigma(\boldsymbol{\lambda}))^2 &= \boldsymbol{\lambda}^\top \left[\sum_{i,k=1}^m \Delta_{ik}^{II} + \sum_{r,p=1}^s \Delta_{rp}^{OO} - 2 \sum_{i=1}^m \sum_{r=1}^s \Delta_{ir}^{IO} \right] \boldsymbol{\lambda} \\ &+ 2 \sum_{j=1}^n \lambda_j \left[\sum_{i=1}^m \sum_{r=1}^s (\text{Cov}(\tilde{x}_{io}, \tilde{y}_{rj}) + \text{Cov}(\tilde{x}_{ij}, \tilde{y}_{ro})) \right. \\ &\quad \left. - \sum_{i,k=1}^m \text{Cov}(\tilde{x}_{io}, \tilde{x}_{kj}) - \sum_{r,p=1}^s \text{Cov}(\tilde{y}_{ro}, \tilde{y}_{pj}) \right] \\ &+ \sum_{i,k=1}^m \text{Cov}(\tilde{x}_{io}, \tilde{x}_{ko}) + \sum_{r,p=1}^s \text{Cov}(\tilde{y}_{ro}, \tilde{y}_{po}) - 2 \sum_{i=1}^m \sum_{r=1}^s \text{Cov}(\tilde{x}_{io}, \tilde{y}_{ro}), \\ (\sigma_i^-(\boldsymbol{\lambda}))^2 &= \boldsymbol{\lambda}^\top \Delta_{ii}^{II} \boldsymbol{\lambda} - 2 \sum_{j=1}^n \lambda_j \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{io}) + \text{Var}(\tilde{x}_{io}), \quad i = 1, \dots, m, \\ (\sigma_r^+(\boldsymbol{\lambda}))^2 &= \boldsymbol{\lambda}^\top \Delta_{rr}^{OO} \boldsymbol{\lambda} - 2 \sum_{j=1}^n \lambda_j \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{ro}) + \text{Var}(\tilde{y}_{ro}), \quad r = 1, \dots, s. \end{aligned}$$

such that

$$\begin{aligned} (\Delta_{ik}^{II})_{jq} &= \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{kq}), \\ (\Delta_{rp}^{OO})_{jq} &= \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{pq}), \\ (\Delta_{ir}^{IO})_{jq} &= (\Delta_{ri}^{OI})_{qj} = \text{Cov}(\tilde{x}_{ij}, \tilde{y}_{rq}), \end{aligned}$$

with $1 \leq j, q \leq n$.

Usage

```

modelstoch_additive_p(datadea,
  alpha = 0.05,
  epsilon = 0.05,
  dmu_eval = NULL,
  dmu_ref = NULL,
  orientation = NULL,
  weight_slack_i = 1,
  weight_slack_o = 1,
  rts = c("crs", "vrs", "nirs", "ndrs", "grs"),
  L = 1,
  U = 1,
  solver = c("alabama", "cccp", "cccp2", "slsqp"),
  give_X = TRUE,
  returnqp = FALSE,
  ...)

```

Arguments

datadea	The data of class <code>deadata_stoch</code> , including n DMUs, and the expected values of m inputs and s outputs.
alpha	A value for parameter <code>alpha</code> .
epsilon	A value for parameter <code>epsilon</code> .
dmu_eval	A numeric vector containing which DMUs have to be evaluated. If <code>NULL</code> (default), all DMUs are considered.
dmu_ref	A numeric vector containing which DMUs are the evaluation reference set. If <code>NULL</code> (default), all DMUs are considered.
orientation	This parameter is either <code>NULL</code> (default) or a string, equal to "io" (input-oriented) or "oo" (output-oriented). It is used to modify the weight slacks. If input-oriented, <code>weight_slack_o</code> are taken 0. If output-oriented, <code>weight_slack_i</code> are taken 0.
weight_slack_i	A value, vector of length m , or matrix $m \times n_e$ (where n_e is the length of <code>dmu_eval</code>) with the weights of the input slacks. If 0, output-oriented.
weight_slack_o	A value, vector of length s , or matrix $s \times n_e$ (where n_e is the length of <code>dmu_eval</code>) with the weights of the output slacks. If 0, input-oriented.
rts	A string, determining the type of returns to scale, equal to "crs" (constant), "vrs" (variable), "nirs" (non-increasing), "ndrs" (non-decreasing) or "grs" (generalized).
L	Lower bound for the generalized returns to scale (grs).
U	Upper bound for the generalized returns to scale (grs).
solver	Character string with the name of the solver used by function <code>solvecop</code> from package <code>optiSolve</code> .
give_X	Logical. If it is <code>TRUE</code> , it uses an initial vector (given by the evaluated DMU) for the solver, except for "cccp". If it is <code>FALSE</code> , the initial vector is given internally by the solver and it is usually randomly generated.

returnqp Logical. If it is TRUE, it returns the quadratic problems (objective function and constraints).

... Other parameters, like the initial vector X, to be passed to the solver.

Value

A list with the results for the evaluated DMUs and other parameters for reproducibility.

Note

The model in this function is the "max" version of the model in Cooper et al. (1998), in the sense that maximizes the sum of positive slacks like the conventional additive model in Cooper et al. (1985). Hence, a DMU is α -stochastically efficient if and only if the optimal objective value of the problem, (objval), is zero (or less than zero).

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References

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Cooper, W.W.; Huang, Z.; Lelas, V.; Li, S.X.; Olesen, O.B. (1998) "Chance Constrained Programming Formulations for Stochastic Characterizations of Efficiency and Dominance in DEA", *Journal of Productivity Analysis*, 9, 53–79. doi:10.1023/A:1018320430249

Cooper, W.W.; Park, K.S.; Pastor, J.T. (1999). "RAM: A Range Adjusted Measure of Inefficiencies for Use with Additive Models, and Relations to Other Models and Measures in DEA". *Journal of Productivity Analysis*, 11, p. 5-42. doi:10.1023/A:1007701304281

Description

It solves the chance constrained super-efficiency additive E-model based on the deterministic super-efficiency additive model from Du et al. (2010), under constant and non-constant returns to scale. Besides, the user can set weights for the input and/or output slacks.

We consider $\mathcal{D} = \{\text{DMU}_1, \dots, \text{DMU}_n\}$ a set of n DMUs with m stochastic inputs and s stochastic outputs. Matrices $\tilde{X} = (\tilde{x}_{ij})$ and $\tilde{Y} = (\tilde{y}_{rj})$ are the input and output data matrices, respectively, where \tilde{x}_{ij} and \tilde{y}_{rj} represent the i -th input and r -th output of the j -th DMU. Moreover, we denote by $X = (x_{ij})$ and $Y = (y_{rj})$ their expected values. In general, we denote vectors by bold-face letters and they are considered as column vectors unless otherwise stated. The 0-vector is denoted by $\mathbf{0}$ and the context determines its dimension.

Given $0 < \alpha < 1$, the program for DMU_o with constant returns to scale is given by

$$\begin{aligned} & \min_{\lambda, \mathbf{t}^-, \mathbf{t}^+} \quad \mathbf{w}^- \mathbf{t}^- + \mathbf{w}^+ \mathbf{t}^+ \\ \text{s.t.} \quad & P \left\{ \left(\tilde{\mathbf{x}}_o - \tilde{X}_{-o} \boldsymbol{\lambda} + \mathbf{t}^- \right)_i \geq 0 \right\} \geq 1 - \alpha, \quad i = 1, \dots, m, \\ & P \left\{ \left(\tilde{Y}_{-o} \boldsymbol{\lambda} - \tilde{\mathbf{y}}_o + \mathbf{t}^+ \right)_r \geq 0 \right\} \geq 1 - \alpha, \quad r = 1, \dots, s, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \quad \mathbf{t}^- \geq \mathbf{0}, \quad \mathbf{t}^+ \geq \mathbf{0}, \end{aligned}$$

where $\tilde{X}_{-o}, \tilde{Y}_{-o}$ are the input and output data matrices, respectively, defined by $\mathcal{D} - \{\text{DMU}_o\}$, $\boldsymbol{\lambda} = (\lambda_1, \dots, \lambda_{o-1}, \lambda_{o+1}, \dots, \lambda_n)^\top$, $\tilde{\mathbf{x}}_o = (\tilde{x}_{1o}, \dots, \tilde{x}_{mo})^\top$ and $\tilde{\mathbf{y}}_o = (\tilde{y}_{1o}, \dots, \tilde{y}_{so})^\top$ are column vectors. Moreover, $\mathbf{s}^-, \mathbf{s}^+$ are column vectors with the slacks, and $\mathbf{w}^-, \mathbf{w}^+$ are positive row vectors with the weights for the slacks. Different returns to scale can be easily considered by adding the corresponding constraints: $\mathbf{e}\boldsymbol{\lambda} = 1$ (VRS), $0 \leq \mathbf{e}\boldsymbol{\lambda} \leq 1$ (NIRS), $\mathbf{e}\boldsymbol{\lambda} \geq 1$ (NDRS) or $L \leq \mathbf{e}\boldsymbol{\lambda} \leq U$ (GRS), with $0 \leq L \leq 1$ and $U \geq 1$, where $\mathbf{e} = (1, \dots, 1)$ is a row vector.

The deterministic equivalent for a multivariate normal distribution of inputs/outputs is given by

$$\begin{aligned} & \min_{\lambda, \mathbf{t}^-, \mathbf{t}^+} \quad \mathbf{w}^- \mathbf{t}^- + \mathbf{w}^+ \mathbf{t}^+ \\ \text{s.t.} \quad & \mathbf{x}_o - X_{-o} \boldsymbol{\lambda} + \mathbf{t}^- + \Phi^{-1}(\alpha) \boldsymbol{\sigma}^-(\boldsymbol{\lambda}) \geq \mathbf{0}, \\ & Y_{-o} \boldsymbol{\lambda} - \mathbf{y}_o + \mathbf{t}^+ + \Phi^{-1}(\alpha) \boldsymbol{\sigma}^+(\boldsymbol{\lambda}) \geq \mathbf{0}, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \quad \mathbf{t}^- \geq \mathbf{0}, \quad \mathbf{t}^+ \geq \mathbf{0}, \end{aligned}$$

where Φ is the standard normal distribution, and

$$\begin{aligned} (\sigma_i^-(\boldsymbol{\lambda}))^2 &= \sum_{\substack{j,q=1 \\ j,q \neq o}}^n \lambda_j \lambda_q \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{iq}) - 2 \sum_{\substack{j=1 \\ j \neq o}}^n \lambda_j \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{io}) \\ &\quad + \text{Var}(\tilde{x}_{io}), \quad i = 1, \dots, m, \\ (\sigma_r^+(\boldsymbol{\lambda}))^2 &= \sum_{\substack{j,q=1 \\ j,q \neq o}}^n \lambda_j \lambda_q \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{rq}) - 2 \sum_{\substack{j=1 \\ j \neq o}}^n \lambda_j \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{ro}) \\ &\quad + \text{Var}(\tilde{y}_{ro}), \quad r = 1, \dots, s. \end{aligned}$$

Usage

```

modelstoch_addsupereff(datadea,
  alpha = 0.05,
  dmu_eval = NULL,
  dmu_ref = NULL,
  orientation = NULL,
  weight_slack_i = NULL,
  weight_slack_o = NULL,
  rts = c("crs", "vrs", "nirs", "ndrs", "grs"),
  L = 1,
  U = 1,
  solver = c("alabama", "cccp", "cccp2", "slsqp"),
  compute_target = TRUE,
  returnqp = FALSE,
  ...)

```

Arguments

<code>datadea</code>	The data of class <code>deadata_stoch</code> , including n DMUs, and the expected values of m inputs and s outputs.
<code>alpha</code>	A value for parameter α .
<code>dmu_eval</code>	A numeric vector containing which DMUs have to be evaluated. If <code>NULL</code> (default), all DMUs are considered.
<code>dmu_ref</code>	A numeric vector containing which DMUs are the evaluation reference set. If <code>NULL</code> (default), all DMUs are considered.
<code>orientation</code>	This parameter is either <code>NULL</code> (default) or a string, equal to "io" (input-oriented) or "oo" (output-oriented). It is used to modify the weight slacks. If input-oriented, <code>weight_slack_o</code> are taken 0. If output-oriented, <code>weight_slack_i</code> are taken 0.
<code>weight_slack_i</code>	A value, vector of length m , or matrix $m \times ne$ (where ne is the length of <code>dmu_eval</code>) with the weights of the input super-slacks (<code>t_input</code>). If 0, output-oriented. If <code>weight_slack_i</code> is the matrix of the inverses of inputs of DMUS in <code>dmu_eval</code> (default), the model is unit invariant.
<code>weight_slack_o</code>	A value, vector of length s , or matrix $s \times ne$ (where ne is the length of <code>dmu_eval</code>) with the weights of the output super-slacks (<code>t_output</code>). If 0, input-oriented. If <code>weight_slack_o</code> is the matrix of the inverses of outputs of DMUS in <code>dmu_eval</code> (default), the model is unit invariant.
<code>rts</code>	A string, determining the type of returns to scale, equal to "crs" (constant), "vrs" (variable), "nirs" (non-increasing), "ndrs" (non-decreasing) or "grs" (generalized).
<code>L</code>	Lower bound for the generalized returns to scale (grs).
<code>U</code>	Upper bound for the generalized returns to scale (grs).
<code>solver</code>	Character string with the name of the solver used by function <code>solvecop</code> from package <code>optiSolve</code> .
<code>compute_target</code>	Logical. If it is <code>TRUE</code> , it computes targets, projections and slacks.

returnqp Logical. If it is TRUE, it returns the quadratic problems (objective function and constraints).

... Other parameters, like the initial vector X , to be passed to the solver.

Value

A list with the results for the evaluated DMUs and other parameters for reproducibility.

Note

A DMU is α -stochastically efficient if and only if the optimal objective value of the problem, (objval), is zero (or less than zero).

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References

Du, J.; Liang, L.; Zhu, J. (2010). "A Slacks-based Measure of Super-efficiency in Data Envelopment Analysis. A Comment", *European Journal of Operational Research*, 204, 694-697. doi:10.1016/j.ejor.2009.12.007

modelstoch_dir

Chance Constrained Directional Models with Stochastic Directions

Description

It solves chance constrained directional models with stochastic directions, under constant, variable, non-increasing, non-decreasing or generalized returns to scale. Inputs and outputs must follow a multivariate normal distribution. By default, models are solved in a two-stage process (slacks are maximized).

We consider $\mathcal{D} = \{DMU_1, \dots, DMU_n\}$ a set of n DMUs with m stochastic inputs and s stochastic outputs. Matrices $\tilde{X} = (\tilde{x}_{ij})$ and $\tilde{Y} = (\tilde{y}_{rj})$ are the input and output data matrices, respectively, where \tilde{x}_{ij} and \tilde{y}_{rj} represent the i -th input and r -th output of the j -th DMU. Moreover, we denote by $X = (x_{ij})$ and $Y = (y_{rj})$ their expected values. In general, we denote vectors by bold-face letters and they are considered as column vectors unless otherwise stated. The 0-vector is denoted by $\mathbf{0}$ and the context determines its dimension.

Given $0 < \alpha < 1$, the first stage program for DMU_o with constant returns to scale is given by

$$\max_{\beta, \lambda} \beta$$

$$\begin{aligned} \text{s.t. } P \left\{ \left(\Theta^-(\beta) \tilde{\mathbf{x}}_o - \tilde{X} \boldsymbol{\lambda} \right)_i \geq 0 \right\} &\geq 1 - \alpha, \quad i = 1, \dots, m, \\ P \left\{ \left(\tilde{Y} \boldsymbol{\lambda} - \Theta^+(\beta) \tilde{\mathbf{y}}_o \right)_r \geq 0 \right\} &\geq 1 - \alpha, \quad r = 1, \dots, s, \\ \boldsymbol{\lambda} &\geq \mathbf{0}, \end{aligned}$$

where $\boldsymbol{\lambda} = (\lambda_1, \dots, \lambda_n)^\top$, $\tilde{\mathbf{x}}_o = (\tilde{x}_{1o}, \dots, \tilde{x}_{mo})^\top$ and $\tilde{\mathbf{y}}_o = (\tilde{y}_{1o}, \dots, \tilde{y}_{so})^\top$ are column vectors, $\Theta^-(\beta) = I_m - \beta D^-$, $\Theta^+(\beta) = I_s + \beta D^+$ (with I_m, I_s identity matrices), and $D^- = \text{diag}(d_1^-, \dots, d_m^-)$, $D^+ = \text{diag}(d_1^+, \dots, d_s^+)$ are diagonal matrices with orientation parameters $d_1^-, \dots, d_m^-, d_1^+, \dots, d_s^+ \geq 0$. Different returns to scale can be easily considered by adding the corresponding constraints: $\mathbf{e}\boldsymbol{\lambda} = 1$ (VRS), $0 \leq \mathbf{e}\boldsymbol{\lambda} \leq 1$ (NIRS), $\mathbf{e}\boldsymbol{\lambda} \geq 1$ (NDRS) or $L \leq \mathbf{e}\boldsymbol{\lambda} \leq U$ (GRS), with $0 \leq L \leq 1$ and $U \geq 1$, where $\mathbf{e} = (1, \dots, 1)$ is a row vector.

The corresponding second stage program is given by

$$\begin{aligned} \max_{\boldsymbol{\lambda}, \mathbf{s}^-, \mathbf{s}^+} \quad & \mathbf{w}^- \mathbf{s}^- + \mathbf{w}^+ \mathbf{s}^+ \\ \text{s.t. } P \left\{ \left(\Theta^-(\beta^*) \tilde{\mathbf{x}}_o - \tilde{X} \boldsymbol{\lambda} - \mathbf{s}^- \right)_i \geq 0 \right\} &= 1 - \alpha, \quad i = 1, \dots, m, \\ P \left\{ \left(\tilde{Y} \boldsymbol{\lambda} - \Theta^+(\beta^*) \tilde{\mathbf{y}}_o - \mathbf{s}^+ \right)_r \geq 0 \right\} &= 1 - \alpha, \quad r = 1, \dots, s, \\ \boldsymbol{\lambda} \geq \mathbf{0}, \mathbf{s}^- \geq \mathbf{0}, \mathbf{s}^+ \geq \mathbf{0}, \end{aligned}$$

where β^* is the optimal objective function of the first stage program, $\mathbf{s}^-, \mathbf{s}^+$ are column vectors with the slacks, and $\mathbf{w}^-, \mathbf{w}^+$ are positive row vectors with the weights for the slacks.

The deterministic equivalents for a multivariate normal distribution of inputs/outputs are given by

$$\begin{aligned} \max_{\beta, \boldsymbol{\lambda}} \quad & \beta \\ \text{s.t. } X \boldsymbol{\lambda} - \Phi^{-1}(\alpha) \boldsymbol{\sigma}^-(\beta, \boldsymbol{\lambda}) &\leq \Theta^-(\beta) \mathbf{x}_o, \\ Y \boldsymbol{\lambda} + \Phi^{-1}(\alpha) \boldsymbol{\sigma}^+(\beta, \boldsymbol{\lambda}) &\geq \Theta^+(\beta) \mathbf{y}_o, \\ \boldsymbol{\lambda} &\geq \mathbf{0}, \end{aligned}$$

and for the second stage,

$$\begin{aligned} \max_{\boldsymbol{\lambda}, \mathbf{s}^-, \mathbf{s}^+} \quad & \mathbf{w}^- \mathbf{s}^- + \mathbf{w}^+ \mathbf{s}^+ \\ \text{s.t. } X \boldsymbol{\lambda} + \mathbf{s}^- - \Phi^{-1}(\alpha) \boldsymbol{\sigma}^-(\beta^*, \boldsymbol{\lambda}) &= \Theta^-(\beta^*) \mathbf{x}_o, \\ Y \boldsymbol{\lambda} - \mathbf{s}^+ + \Phi^{-1}(\alpha) \boldsymbol{\sigma}^+(\beta^*, \boldsymbol{\lambda}) &= \Theta^+(\beta^*) \mathbf{y}_o, \\ \boldsymbol{\lambda} \geq \mathbf{0}, \mathbf{s}^- \geq \mathbf{0}, \mathbf{s}^+ \geq \mathbf{0}, \end{aligned}$$

where Φ is the standard normal distribution, and

$$\begin{aligned} (\sigma_i^-(\beta, \boldsymbol{\lambda}))^2 &= \sum_{j,q=1}^n \lambda_j \lambda_q \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{iq}) - 2(1 - \beta d_i^-) \sum_{j=1}^n \lambda_j \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{io}) \\ &\quad + (1 - \beta d_i^-)^2 \text{Var}(\tilde{x}_{io}), \quad i = 1, \dots, m, \\ (\sigma_r^+(\beta, \boldsymbol{\lambda}))^2 &= \sum_{j,q=1}^n \lambda_j \lambda_q \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{rq}) - 2(1 + \beta d_r^+) \sum_{j=1}^n \lambda_j \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{ro}) \\ &\quad + (1 + \beta d_r^+)^2 \text{Var}(\tilde{y}_{ro}), \quad r = 1, \dots, s. \end{aligned}$$

Usage

```

modelstoch_dir(datadea,
               alpha = 0.05,
               dmu_eval = NULL,
               dmu_ref = NULL,
               d_input = 1,
               d_output = 1,
               rts = c("crs", "vrs", "nirs", "ndrs", "grs"),
               L = 1,
               U = 1,
               solver = c("alabama", "cccp", "cccp2", "slsqp"),
               give_X = TRUE,
               maxslack = TRUE,
               weight_slack_i = 1,
               weight_slack_o = 1,
               compute_target = TRUE,
               returnqp = FALSE,
               silent_ud = FALSE,
               ...)

```

Arguments

<code>datadea</code>	The data of class <code>deadata_stoch</code> , including n DMUs, and the expected values of m inputs and s outputs.
<code>alpha</code>	A value for parameter <code>alpha</code> .
<code>dmu_eval</code>	A numeric vector containing which DMUs have to be evaluated. If <code>NULL</code> (default), all DMUs are considered.
<code>dmu_ref</code>	A numeric vector containing which DMUs are the evaluation reference set. If <code>NULL</code> (default), all DMUs are considered.
<code>d_input</code>	A value, vector of length m , or matrix $m \times n_e$ (where n_e is the length of <code>dmu_eval</code>) with the input orientation parameters. If <code>d_input == 1</code> (default) and <code>dir_output == 0</code> , it is equivalent to input oriented ($\beta = 1 - \text{efficiency}$).
<code>d_output</code>	A value, vector of length s , or matrix $s \times n_e$ (where n_e is the length of <code>dmu_eval</code>) with the output orientation parameters. If <code>d_input == 0</code> and <code>d_output == 1</code> (default), it is equivalent to output oriented ($\beta = \text{efficiency} - 1$).
<code>rts</code>	A string, determining the type of returns to scale, equal to "crs" (constant), "vrs" (variable), "nirs" (non-increasing), "ndrs" (non-decreasing) or "grs" (generalized).
<code>L</code>	Lower bound for the generalized returns to scale (grs).
<code>U</code>	Upper bound for the generalized returns to scale (grs).
<code>solver</code>	Character string with the name of the solver used by function <code>solvecop</code> from package <code>optiSolve</code> .
<code>give_X</code>	Logical. If it is <code>TRUE</code> , it uses an initial vector (given by the evaluated DMU) for the solver, except for "cccp". If it is <code>FALSE</code> , the initial vector is given internally by the solver and it is usually randomly generated.

maxslack	Logical. If it is TRUE, it computes the max slack solution.
weight_slack_i	A value, vector of length m , or matrix $m \times n_e$ (where n_e is the length of <code>dmu_eval</code>) with the weights of the input slacks for the max slack solution.
weight_slack_o	A value, vector of length s , or matrix $s \times n_e$ (where n_e is the length of <code>dmu_eval</code>) with the weights of the output slacks for the max slack solution.
compute_target	Logical. If it is TRUE, it computes targets of the max slack solution.
returnqp	Logical. If it is TRUE, it returns the quadratic problems (objective function and constraints) of stage 1.
silent_ud	Logical, to avoid warnings related with undesirable variables.
...	Other parameters, like the initial vector X , to be passed to the solver.

Value

A list with the results for the evaluated DMUs and other parameters for reproducibility.

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References

Bolós, V.J.; Benítez, R.; Coll-Serrano, V. (2024). "Chance constrained directional models in stochastic data envelopment analysis", *Operations Research Perspectives*, 12, 100307.. doi:[10.1016/j.orp.2024.100307](https://doi.org/10.1016/j.orp.2024.100307)

Examples

```
# Example 1.
library(deaR)
data("Coll_Blasco_2006")
ni <- 2 # number of inputs
no <- 2 # number of outputs
data_example <- make_deadata(datadea = Coll_Blasco_2006,
                             ni = ni,
                             no = no)
nd <- length(data_example$dmunames) # number of DMUs
var_input <- matrix(1, nrow = ni, ncol = nd)
var_output <- matrix(1, nrow = no, ncol = nd)
data_stoch <- make_deadata_stoch(datadea = data_example,
                                var_input = var_input,
                                var_output = var_output)
Collstochdir <- modelstoch_dir(data_stoch)
```

Description

It solves chance constrained directional models with deterministic directions, under constant, variable, non-increasing, non-decreasing or generalized returns to scale. Inputs and outputs must follow a multivariate normal distribution. By default, models are solved in a two-stage process (slacks are maximized).

We consider $\mathcal{D} = \{\text{DMU}_1, \dots, \text{DMU}_n\}$ a set of n DMUs with m stochastic inputs and s stochastic outputs. Matrices $\tilde{X} = (\tilde{x}_{ij})$ and $\tilde{Y} = (\tilde{y}_{rj})$ are the input and output data matrices, respectively, where \tilde{x}_{ij} and \tilde{y}_{rj} represent the i -th input and r -th output of the j -th DMU. Moreover, we denote by $X = (x_{ij})$ and $Y = (y_{rj})$ their expected values. In general, we denote vectors by bold-face letters and they are considered as column vectors unless otherwise stated. The 0-vector is denoted by $\mathbf{0}$ and the context determines its dimension.

Given $0 < \alpha < 1$, the first stage program for DMU_o with constant returns to scale is given by

$$\begin{aligned} & \max_{\beta, \boldsymbol{\lambda}} \beta \\ \text{s.t. } & P \left\{ \left(\tilde{\mathbf{x}}_o - \beta \mathbf{g}^- - \tilde{X} \boldsymbol{\lambda} \right)_i \geq 0 \right\} \geq 1 - \alpha, \quad i = 1, \dots, m, \\ & P \left\{ \left(\tilde{\mathbf{y}}_o + \beta \mathbf{g}^+ - \tilde{Y} \boldsymbol{\lambda} \right)_r \leq 0 \right\} \geq 1 - \alpha, \quad r = 1, \dots, s, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \end{aligned}$$

where $\boldsymbol{\lambda} = (\lambda_1, \dots, \lambda_n)^\top$, $\tilde{\mathbf{x}}_o = (\tilde{x}_{1o}, \dots, \tilde{x}_{mo})^\top$ and $\tilde{\mathbf{y}}_o = (\tilde{y}_{1o}, \dots, \tilde{y}_{so})^\top$ are column vectors, and $\mathbf{g} = (-\mathbf{g}^-, \mathbf{g}^+) \neq \mathbf{0}$ is a preassigned direction (with $\mathbf{g}^- \in \mathbb{R}^m$ and $\mathbf{g}^+ \in \mathbb{R}^s$ non-negative column vectors). Different returns to scale can be easily considered by adding the corresponding constraints: $\mathbf{e}\boldsymbol{\lambda} = 1$ (VRS), $0 \leq \mathbf{e}\boldsymbol{\lambda} \leq 1$ (NIRS), $\mathbf{e}\boldsymbol{\lambda} \geq 1$ (NDRS) or $L \leq \mathbf{e}\boldsymbol{\lambda} \leq U$ (GRS), with $0 \leq L \leq 1$ and $U \geq 1$, where $\mathbf{e} = (1, \dots, 1)$ is a row vector.

The corresponding second stage program is given by

$$\begin{aligned} & \max_{\boldsymbol{\lambda}, \mathbf{s}^-, \mathbf{s}^+} \mathbf{w}^- \mathbf{s}^- + \mathbf{w}^+ \mathbf{s}^+ \\ \text{s.t. } & P \left\{ \left(\tilde{\mathbf{x}}_o - \beta^* \mathbf{g}^- - \tilde{X} \boldsymbol{\lambda} - \mathbf{s}^- \right)_i \geq 0 \right\} \geq 1 - \alpha, \quad i = 1, \dots, m, \\ & P \left\{ \left(\tilde{\mathbf{y}}_o + \beta^* \mathbf{g}^+ - \tilde{Y} \boldsymbol{\lambda} + \mathbf{s}^+ \right)_r \leq 0 \right\} \geq 1 - \alpha, \quad r = 1, \dots, s, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \mathbf{s}^- \geq \mathbf{0}, \mathbf{s}^+ \geq \mathbf{0}, \end{aligned}$$

where β^* is the optimal objective function of the first stage program, $\mathbf{s}^-, \mathbf{s}^+$ are column vectors with the slacks, and $\mathbf{w}^-, \mathbf{w}^+$ are positive row vectors with the weights for the slacks.

The deterministic equivalents for a multivariate normal distribution of inputs/outputs are given by

$$\max_{\beta, \boldsymbol{\lambda}} \beta$$

$$\begin{aligned}
\text{s.t. } & \beta \mathbf{g}^- + X\boldsymbol{\lambda} - \Phi^{-1}(\alpha)\boldsymbol{\sigma}^-(\boldsymbol{\lambda}) \leq \mathbf{x}_o, \\
& -\beta \mathbf{g}^+ + Y\boldsymbol{\lambda} + \Phi^{-1}(\alpha)\boldsymbol{\sigma}^+(\boldsymbol{\lambda}) \geq \mathbf{y}_o, \\
& \boldsymbol{\lambda} \geq \mathbf{0},
\end{aligned}$$

and for the second stage,

$$\begin{aligned}
& \max_{\boldsymbol{\lambda}, \mathbf{s}^-, \mathbf{s}^+} \quad \mathbf{w}^- \mathbf{s}^- + \mathbf{w}^+ \mathbf{s}^+ \\
\text{s.t. } & \beta^* \mathbf{g}^- + X\boldsymbol{\lambda} + \mathbf{s}^- - \Phi^{-1}(\alpha)\boldsymbol{\sigma}^-(\boldsymbol{\lambda}) = \mathbf{x}_o, \\
& -\beta^* \mathbf{g}^+ + Y\boldsymbol{\lambda} - \mathbf{s}^+ + \Phi^{-1}(\alpha)\boldsymbol{\sigma}^+(\boldsymbol{\lambda}) = \mathbf{y}_o, \\
& \boldsymbol{\lambda} \geq \mathbf{0}, \mathbf{s}^- \geq \mathbf{0}, \mathbf{s}^+ \geq \mathbf{0},
\end{aligned}$$

where Φ is the standard normal distribution, and

$$\begin{aligned}
(\sigma_i^-(\boldsymbol{\lambda}))^2 &= \sum_{j,q=1}^n \lambda_j \lambda_q \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{iq}) - 2 \sum_{j=1}^n \lambda_j \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{io}) \\
&\quad + \text{Var}(\tilde{x}_{io}), \quad i = 1, \dots, m, \\
(\sigma_r^+(\boldsymbol{\lambda}))^2 &= \sum_{j,q=1}^n \lambda_j \lambda_q \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{rq}) - 2 \sum_{j=1}^n \lambda_j \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{ro}) \\
&\quad + \text{Var}(\tilde{y}_{ro}), \quad r = 1, \dots, s.
\end{aligned}$$

Usage

```

modelstoch_dir_dd(datadea,
  alpha = 0.05,
  dmu_eval = NULL,
  dmu_ref = NULL,
  dir_input = NULL,
  dir_output = NULL,
  rts = c("crs", "vrs", "nirs", "ndrs", "grs"),
  L = 1,
  U = 1,
  solver = c("alabama", "cccp", "cccp2", "slsqp"),
  give_X = TRUE,
  maxslack = TRUE,
  weight_slack_i = 1,
  weight_slack_o = 1,
  compute_target = TRUE,
  returnqp = FALSE,
  silent_ud = FALSE,
  ...)

```

Arguments

datadea	The data of class deadata_stoch, including n DMUs, and the expected values of m inputs and s outputs.
alpha	A value for parameter alpha.
dmu_eval	A numeric vector containing which DMUs have to be evaluated. If NULL (default), all DMUs are considered.
dmu_ref	A numeric vector containing which DMUs are the evaluation reference set. If NULL (default), all DMUs are considered.
dir_input	A value, vector of length m, or matrix m x ne (where ne is the length of dmu_eval) with the input directions. If dir_input == input matrix (of DMUS in dmu_eval) and dir_output == 0, it is equivalent to input oriented (beta = 1 - efficiency). If dir_input is omitted, input matrix (of DMUS in dmu_eval) is assigned.
dir_output	A value, vector of length s, or matrix s x ne (where ne is the length of dmu_eval) with the output directions. If dir_input == 0 and dir_output == output matrix (of DMUS in dmu_eval), it is equivalent to output oriented (beta = efficiency - 1). If dir_output is omitted, output matrix (of DMUS in dmu_eval) is assigned.
rts	A string, determining the type of returns to scale, equal to "crs" (constant), "vrs" (variable), "nirs" (non-increasing), "ndrs" (non-decreasing) or "grs" (generalized).
L	Lower bound for the generalized returns to scale (grs).
U	Upper bound for the generalized returns to scale (grs).
solver	Character string with the name of the solver used by function solvecop from package optiSolve.
give_X	Logical. If it is TRUE, it uses an initial vector (given by the evaluated DMU) for the solver, except for "cccp". If it is FALSE, the initial vector is given internally by the solver and it is usually randomly generated.
maxslack	Logical. If it is TRUE, it computes the max slack solution.
weight_slack_i	A value, vector of length m, or matrix m x ne (where ne is the length of dmu_eval) with the weights of the input slacks for the max slack solution.
weight_slack_o	A value, vector of length s, or matrix s x ne (where ne is the length of dmu_eval) with the weights of the output slacks for the max slack solution.
compute_target	Logical. If it is TRUE, it computes targets of the max slack solution.
returnqp	Logical. If it is TRUE, it returns the quadratic problems (objective function and constraints) of stage 1.
silent_ud	Logical, to avoid warnings related with undesirable variables.
...	Other parameters, like the initial vector X, to be passed to the solver.

Value

A list with the results for the evaluated DMUs and other parameters for reproducibility.

Author(s)

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References

Bolós, V.J.; Benítez, R.; Coll-Serrano, V. (2024). "Chance constrained directional models in stochastic data envelopment analysis", *Operations Research Perspectives*, 12, 100307.. doi:10.1016/j.orp.2024.100307

Examples

```
# Example 1.
library(deaR)
data("Coll_Blasco_2006")
ni <- 2 # number of inputs
no <- 2 # number of outputs
data_example <- make_deadata(datadea = Coll_Blasco_2006,
                             ni = ni,
                             no = no)
nd <- length(data_example$dmunames) # number of DMUs
var_input <- matrix(1, nrow = ni, ncol = nd)
var_output <- matrix(1, nrow = no, ncol = nd)
data_stoch <- make_deadata_stoch(datadea = data_example,
                                var_input = var_input,
                                var_output = var_output)
Collstochdirdd <- modelstoch_dir_dd(data_stoch)
```

modelstoch_radial

Chance Constrained Radial Models

Description

It solves input and output oriented chance constrained radial DEA models under constant (CCR model), variable (BCC model), non-increasing, non-decreasing or generalized returns to scale, based on the model in Cooper et al. (2002). By default, models are solved in a two-stage process (slacks are maximized).

We consider $\mathcal{D} = \{\text{DMU}_1, \dots, \text{DMU}_n\}$ a set of n DMUs with m stochastic inputs and s stochastic outputs. Matrices $\tilde{X} = (\tilde{x}_{ij})$ and $\tilde{Y} = (\tilde{y}_{rj})$ are the input and output data matrices, respectively, where \tilde{x}_{ij} and \tilde{y}_{rj} represent the i -th input and r -th output of the j -th DMU. Moreover, we denote by $X = (x_{ij})$ and $Y = (y_{rj})$ their expected values. In general, we denote vectors by bold-face

letters and they are considered as column vectors unless otherwise stated. The 0-vector is denoted by $\mathbf{0}$ and the context determines its dimension.

Given $0 < \alpha < 1$, the first stage program for DMU_o with constant returns to scale is given by

$$\begin{aligned} & \min_{\theta, \boldsymbol{\lambda}} \theta \\ \text{s.t. } & P \left\{ \left(\theta \tilde{\mathbf{x}}_o - \tilde{X} \boldsymbol{\lambda} \right)_i \geq 0 \right\} \geq 1 - \alpha, \quad i = 1, \dots, m, \\ & P \left\{ \left(\tilde{Y} \boldsymbol{\lambda} - \tilde{\mathbf{y}}_o \right)_r \geq 0 \right\} \geq 1 - \alpha, \quad r = 1, \dots, s, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \end{aligned}$$

where $\boldsymbol{\lambda} = (\lambda_1, \dots, \lambda_n)^\top$, $\tilde{\mathbf{x}}_o = (\tilde{x}_{1o}, \dots, \tilde{x}_{mo})^\top$ and $\tilde{\mathbf{y}}_o = (\tilde{y}_{1o}, \dots, \tilde{y}_{so})^\top$ are column vectors. Different returns to scale can be easily considered by adding the corresponding constraints: $\mathbf{e}\boldsymbol{\lambda} = 1$ (VRS), $0 \leq \mathbf{e}\boldsymbol{\lambda} \leq 1$ (NIRS), $\mathbf{e}\boldsymbol{\lambda} \geq 1$ (NDRS) or $L \leq \mathbf{e}\boldsymbol{\lambda} \leq U$ (GRS), with $0 \leq L \leq 1$ and $U \geq 1$, where $\mathbf{e} = (1, \dots, 1)$ is a row vector.

The corresponding second stage program is given by

$$\begin{aligned} & \max_{\boldsymbol{\lambda}, \mathbf{s}^-, \mathbf{s}^+} \mathbf{w}^- \mathbf{s}^- + \mathbf{w}^+ \mathbf{s}^+ \\ \text{s.t. } & P \left\{ \left(\theta^* \tilde{\mathbf{x}}_o - \tilde{X} \boldsymbol{\lambda} - \mathbf{s}^- \right)_i \geq 0 \right\} = 1 - \alpha, \quad i = 1, \dots, m, \\ & P \left\{ \left(\tilde{Y} \boldsymbol{\lambda} - \tilde{\mathbf{y}}_o - \mathbf{s}^+ \right)_r \geq 0 \right\} = 1 - \alpha, \quad r = 1, \dots, s, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \mathbf{s}^- \geq \mathbf{0}, \mathbf{s}^+ \geq \mathbf{0}, \end{aligned}$$

where θ^* is the optimal objective function of the first stage program, $\mathbf{s}^-, \mathbf{s}^+$ are column vectors with the slacks, and $\mathbf{w}^-, \mathbf{w}^+$ are positive row vectors with the weights for the slacks.

The deterministic equivalents for a multivariate normal distribution of inputs/outputs are given by

$$\begin{aligned} & \min_{\theta, \boldsymbol{\lambda}} \theta \\ \text{s.t. } & X \boldsymbol{\lambda} - \Phi^{-1}(\alpha) \boldsymbol{\sigma}^-(\theta, \boldsymbol{\lambda}) \leq \theta \mathbf{x}_o, \\ & Y \boldsymbol{\lambda} + \Phi^{-1}(\alpha) \boldsymbol{\sigma}^+(\boldsymbol{\lambda}) \geq \mathbf{y}_o, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \end{aligned}$$

and for the second stage,

$$\begin{aligned} & \max_{\boldsymbol{\lambda}, \mathbf{s}^-, \mathbf{s}^+} \mathbf{w}^- \mathbf{s}^- + \mathbf{w}^+ \mathbf{s}^+ \\ \text{s.t. } & X \boldsymbol{\lambda} + \mathbf{s}^- - \Phi^{-1}(\alpha) \boldsymbol{\sigma}^-(\theta^*, \boldsymbol{\lambda}) = \theta^* \mathbf{x}_o, \\ & Y \boldsymbol{\lambda} - \mathbf{s}^+ + \Phi^{-1}(\alpha) \boldsymbol{\sigma}^+(\boldsymbol{\lambda}) = \mathbf{y}_o, \\ & \boldsymbol{\lambda} \geq \mathbf{0}, \mathbf{s}^- \geq \mathbf{0}, \mathbf{s}^+ \geq \mathbf{0}, \end{aligned}$$

where Φ is the standard normal distribution, and

$$\begin{aligned} (\sigma_i^-(\theta, \boldsymbol{\lambda}))^2 &= \sum_{j,q=1}^n \lambda_j \lambda_q \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{iq}) - 2\theta \sum_{j=1}^n \lambda_j \text{Cov}(\tilde{x}_{ij}, \tilde{x}_{io}) \\ &\quad + \theta^2 \text{Var}(\tilde{x}_{io}), \quad i = 1, \dots, m, \\ (\sigma_r^+(\boldsymbol{\lambda}))^2 &= \sum_{j,q=1}^n \lambda_j \lambda_q \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{rq}) - 2 \sum_{j=1}^n \lambda_j \text{Cov}(\tilde{y}_{rj}, \tilde{y}_{ro}) \\ &\quad + \text{Var}(\tilde{y}_{ro}), \quad r = 1, \dots, s. \end{aligned}$$

Usage

```

modelstoch_radial(datadea,
  alpha = 0.05,
  dmu_eval = NULL,
  dmu_ref = NULL,
  orientation = c("io", "oo"),
  rts = c("crs", "vrs", "nirs", "ndrs", "grs"),
  L = 1,
  U = 1,
  solver = c("alabama", "cccp", "cccp2", "slsqp"),
  give_X = TRUE,
  maxslack = TRUE,
  weight_slack_i = 1,
  weight_slack_o = 1,
  vtrans_i = NULL,
  vtrans_o = NULL,
  compute_target = TRUE,
  returnqp = FALSE,
  silent_ud = FALSE,
  ...)

```

Arguments

<code>datadea</code>	The data of class <code>deadata_stoch</code> , including <code>n</code> DMUs, and the expected values of <code>m</code> inputs and <code>s</code> outputs.
<code>alpha</code>	A value for parameter <code>alpha</code> .
<code>dmu_eval</code>	A numeric vector containing which DMUs have to be evaluated. If <code>NULL</code> (default), all DMUs are considered.
<code>dmu_ref</code>	A numeric vector containing which DMUs are the evaluation reference set. If <code>NULL</code> (default), all DMUs are considered.
<code>orientation</code>	A string, equal to "io" (input oriented) or "oo" (output oriented).
<code>rts</code>	A string, determining the type of returns to scale, equal to "crs" (constant), "vrs" (variable), "nirs" (non-increasing), "ndrs" (non-decreasing) or "grs" (generalized).
<code>L</code>	Lower bound for the generalized returns to scale (grs).
<code>U</code>	Upper bound for the generalized returns to scale (grs).
<code>solver</code>	Character string with the name of the solver used by function <code>solvecop</code> from package <code>optiSolve</code> .
<code>give_X</code>	Logical. If it is <code>TRUE</code> , it uses an initial vector (given by the evaluated DMU) for the solver, except for "cccp". If it is <code>FALSE</code> , the initial vector is given internally by the solver and it is usually randomly generated.
<code>maxslack</code>	Logical. If it is <code>TRUE</code> , it computes the max slack solution.
<code>weight_slack_i</code>	A value, vector of length <code>m</code> , or matrix <code>m x ne</code> (where <code>ne</code> is the length of <code>dmu_eval</code>) with the weights of the input slacks for the max slack solution.

weight_slack_o	A value, vector of length s, or matrix s x ne (where ne is the length of dmu_eval) with the weights of the output slacks for the max slack solution.
vtrans_i	Numeric vector of translation for undesirable inputs. If vtrans_i[i] is NA, then it applies the "max + 1" translation to the i-th undesirable input. If vtrans_i is a constant, then it applies the same translation to all undesirable inputs. If vtrans_i is NULL, then it applies the "max + 1" translation to all undesirable inputs.
vtrans_o	Numeric vector of translation for undesirable outputs, analogous to vtrans_i, but applied to outputs.
compute_target	Logical. If it is TRUE, it computes targets of the max slack solution.
returnqp	Logical. If it is TRUE, it returns the quadratic problems (objective function and constraints) of stage 1.
silent_ud	Logical, to avoid warnings related with undesirable variables.
...	Other parameters, like the initial vector X, to be passed to the solver.

Value

A list with the results for the evaluated DMUs and other parameters for reproducibility.

Author(s)

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References

Cooper, W.W.; Deng, H.; Huang, Z.; Li, S.X. (2002). "Chance constrained programming approaches to technical efficiencies and inefficiencies in stochastic data envelopment analysis", *Journal of the Operational Research Society*, 53:12, 1347-1356. doi:10.1057/palgrave.jors.2601433

El-Demerdash, B.E.; El-Khodary, I.A.; Tharwat, A.A. (2013). "Developing a Stochastic Input Oriented Data Envelopment Analysis (SIODEA) Model", *International Journal of Advanced Computer Science and Applications*, Vol.4, No. 4, 40-44.

Examples

```
# Example 1.
library(deaR)
data("Coll_Blasco_2006")
ni <- 2 # number of inputs
no <- 2 # number of outputs
data_example <- make_deadata(datadea = Coll_Blasco_2006,
                             ni = ni,
                             no = no)
nd <- length(data_example$dmunames) # number of DMUs
```

```

var_input <- matrix(1, nrow = ni, ncol = nd)
var_output <- matrix(1, nrow = no, ncol = nd)
data_stoch <- make_deadata_stoch(datadea = data_example,
                               var_input = var_input,
                               var_output = var_output)
Collstoch <- modelstoch_radial(data_stoch)

# Example 2. Deterministic data with one stochastic input.
# Replication of results in El-Demerdash et al. (2013).
library(deaR)
dmunames <- c("A", "B", "C")
nd <- length(dmunames) # Number of DMUs
inputnames <- c("Professors", "Budget")
ni <- length(inputnames) # Number of Inputs
outputnames <- c("Diplomas", "Bachelors", "Masters")
no <- length(outputnames) # Number of Outputs
X <- matrix(c(5, 14, 8, 15, 7, 12),
            nrow = ni, ncol = nd, dimnames = list(inputnames, dmunames))
Y <- matrix(c(9, 4, 16, 5, 7, 10, 4, 9, 13),
            nrow = no, ncol = nd, dimnames = list(outputnames, dmunames))
datadea <- make_deadata(inputs = X,
                       outputs = Y)
covX <- array(0, dim = c(2, 3, 3))
# The 2nd input is stochastic.
# Since the corresponding 3x3 covariances matrix is symmetric, only values
# above the diagonal are necessary.
covX[2, 1, ] <- c(1.4, 0.9, 0.6)
covX[2, 2, 2:3] <- c(1.5, 0.7)
covX[2, 3, 3] <- 1.2
# Alternatively (note that values below the diagonal are ignored).
covX[2, , ] <- matrix(c(1.4, 0.9, 0.6, 0, 1.5, 0.7, 0, 0, 1.2),
                     byrow = TRUE)
datadea_stoch <- make_deadata_stoch(datadea,
                                   cov_input = covX)
res <- modelstoch_radial(datadea_stoch, rts = "vrs")

```

modelstoch_radial_supereff

Chance Constrained Radial Super-efficiency Models

Description

Solve chance constrained radial super-efficiency DEA models, based on the Cooper et al. (2002) chance constrained radial efficiency models. Analogously to the deterministic case, it removes the evaluated DMU from the set of reference DMUs `dmu_ref` with respect to which it is evaluated.

Usage

```
modelstoch_radial_supereff(datadea,
                           dmu_eval = NULL,
                           dmu_ref = NULL,
                           ...)
```

Arguments

datadea	The data of class <code>deadata_stoch</code> with the expected values of inputs and outputs.
dmu_eval	A numeric vector containing which DMUs have to be evaluated. If <code>NULL</code> (default), all DMUs are considered.
dmu_ref	A numeric vector containing which DMUs are the evaluation reference set. If <code>NULL</code> (default), all DMUs are considered.
...	Model parameters like <code>orientation</code> or <code>rts</code> , and other parameters to be passed to the solver.

Value

A list with the results for the evaluated DMUs and other parameters for reproducibility.

Note

Radial super-efficiency chance constrained model under non constant (`vrs`, `nirs`, `ndrs`, `grs`) returns to scale can be unfeasible for certain DMUs.

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References

Cooper, W.W.; Deng, H.; Huang, Z.; Li, S.X. (2002). "Chance constrained programming approaches to technical efficiencies and inefficiencies in stochastic data envelopment analysis", *Journal of the Operational Research Society*, 53:12, 1347-1356.

See Also

[modelstoch_radial](#)

Examples

```
# Example 1.
library(deaR)
ni = 2
no = 1
datatext <- make_deadata(Textile, ni = 2, no = 1)
nd <- length(datatext$dmunames)
# Compute variances
mean_i <- apply(datatext$input, MARGIN = 1, FUN = mean)
mean_o <- mean(datatext$output)
var_i1 <- sum((datatext$input[1, ] - mean_i[1]) ^ 2) / (nd - 1)
var_i2 <- sum((datatext$input[2, ] - mean_i[2]) ^ 2) / (nd - 1)
var_o <- sum((datatext$output - mean_o) ^ 2) / (nd - 1)
var_input <- matrix(rep(c(var_i1, var_i2), nd),
                    nrow = ni,
                    ncol = nd)
var_output <- matrix(var_o,
                     nrow = no,
                     ncol = nd)
datatext_stoch <- make_deadata_stoch(datatext,
                                    var_input = var_input,
                                    var_output = var_output)
res <- modelstoch_radial_supereff(datatext_stoch, orientation = "oo")
```

Textile

Data: Cooper et al. (2001).

Description

Data of textile industries collected from the Statistical Year Book of China of the Chinese Bureau of Statistics. Each year is treated as a DMU.

Usage

```
data("Textile")
```

Format

Data frame with 17 rows and 4 columns. Definition of inputs (X) and output (Y):

X1 = Labor Expressed in units of 1000 persons.

X2 = Capital Stated in units of 1 million Ren Min Bi (Chinese monetary unit) adjusted to 1991 prices.

Y = Output Stated in units of 1 million Ren Min Bi (Chinese monetary unit) adjusted to 1991 prices.

Author(s)

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Source

Cooper, W.W.; Denga, H.; Gua, B.; Lib, S.; Thrall, R.M. (2001). "Using DEA to improve the management of congestion in Chinese industries (1981-1997)", *Socio-Economic Planning Sciences*, 35(4), 227-242.

See Also

[make_deadata_stoch, modelstoch_radial](#)

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